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Spivak's Calculus On Manifolds: Solutions Manual Thomas Hughes August 2017. Chapter 1 Functions on Euclidean Space 1.1 Prove that  $\|x\|_p = \sum_{i=1}^n |x_i|$  Proof. If  $e_1, e_2, \dots, e_n$  is the usual basis on  $\mathbb{R}^n$ , then we can write  $x = x_1 e_1 + x_2 e_2 + \dots + x_n e_n$  and thus  $\|x\|_p = \sum_{i=1}^n |x_i| = \sum_{i=1}^n |x_i| e_i = \sum_{i=1}^n |x_i| e_i$  1.2 When does equality hold in Theorem 1-1(3)? Proof.

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on some subinterval of  $(a, b)$ . Expanding out gives  $a^2 + f^2 - 2af + g^2 - 2ag + 2fg > 0$  for all  $x$ . Since the quadratic has no solutions, it must be that its discriminant is negative. c. Let  $a > 0$ ,  $b > 0$  ...

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4 CHAPTER 1 FUNCTIONS ON EUCLIDEAN SPACE | Exercise 8 (1-8). If  $x, y \in \mathbb{R}^n$  are non-zero, the angle between  $x$  and  $y$ , denoted  $\angle(x, y)$ , is defined as  $\arccos \frac{|x \cdot y|}{\|x\| \|y\|}$ , which makes sense by Theorem 1-1 (2). The linear transformation  $T$  is angle preserving if  $T$  is 1-1, and for  $x, y \neq 0$  we have  $\angle(Tx, Ty) = \angle(x, y)$ . a. Prove that if  $T$  is norm preserving, then  $T$  is angle preserving. b. If there is a basis  $x$

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