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Norman S. Nise teaches in the Electrical and Computer Engineering Department at California State Polytechnic University, Pomona. In addition to being the author of Control Systems Engineering, Professor Nise has contributed to the CRC publications The Engineering Handbook, The Control Handbook, and The Electrical Engineering Handbook.

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Control Systems Engineering, now in its Fifth Edition, takes a practical approach to control systems engineering. Presenting clear and complete explanations, the text shows you how to analyze and design feedback control systems that support today's modern technology. By working with the same physical system in each chapter, the book's progressive case studies give you a realistic view of each stage of the control design process while a combination of qualitative and quantitative explanations provide insight into the design of parameters and system configurations. Best of all, you'll get extensive practice in using MATLAB, Simulink, and the SISO Design Tool--industry standards that you will use in your future career.

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The Book Provides An Integrated Treatment Of Continuous-Time And Discrete-Time Systems For Two Courses At Undergraduate Level Or One Course At Postgraduate Level. The Stress Is On The Interdisciplinary Nature Of The Subject And Examples Have Been Drawn From Various Engineering Disciplines To Illustrate The Basic System Concepts. A Strong Emphasis Is Laid On Modeling Of Practical Systems Involving Hardware; Control Components Of A Wide Variety Are Comprehensively Covered. Time And Frequency Domain Techniques Of Analysis And Design Of Control Systems Have Been Exhaustively Treated And Their Interrelationship Established. Adequate Breadth And Depth Is Made Available For A Second Course. The Coverage Includes Digital Control Systems: Analysis, Stability And Classical Design; State Variables For Both Continuous-Time And Discrete-Time Systems; Observers And Pole-Placement Design; Liapunov Stability; Optimal Control; And Recent Advances In Control Systems: Adaptive Control, Fuzzy Logic Control, Neural Network Control. Salient Features \* State Variables Concept Introduced Early In Chapter 2 \* Examples And Problems Around Obsolete Technology Updated. New Examples Added \* Robotics Modeling And Control Included \* Pid Tuning Procedure Well Explained And Illustrated \* Robust Control Introduced In A Simple And Easily Understood Style \* State Variable Formulation And Design Simplified And Generalizations Built On Examples \* Digital Control; Both Classical And Modern Approaches, Covered In Depth \* A Chapter On Adaptive, Fuzzy Logic And Neural Network Control, Amenable To Undergraduate Level Use, Included \* An Appendix On Matlab With Examples From Time And Frequency Domain Analysis And Design, Included

Introduction to state-space methods covers feedback control; state-space representation of dynamic systems and dynamics of linear systems; frequency-domain analysis; controllability and observability; shaping the dynamic response; more. 1986 edition.

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This best-selling introduction to automatic control systems has been updated to reflect the increasing use of computer-aided learning and design, and revised to feature a more accessible approach – without sacrificing depth.

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